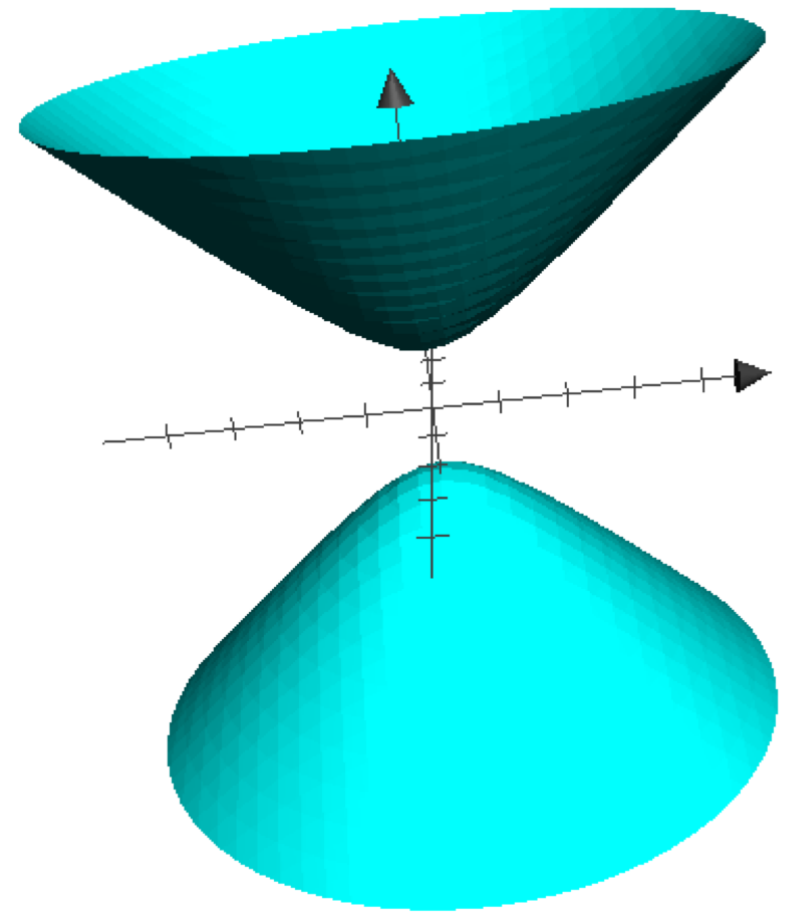
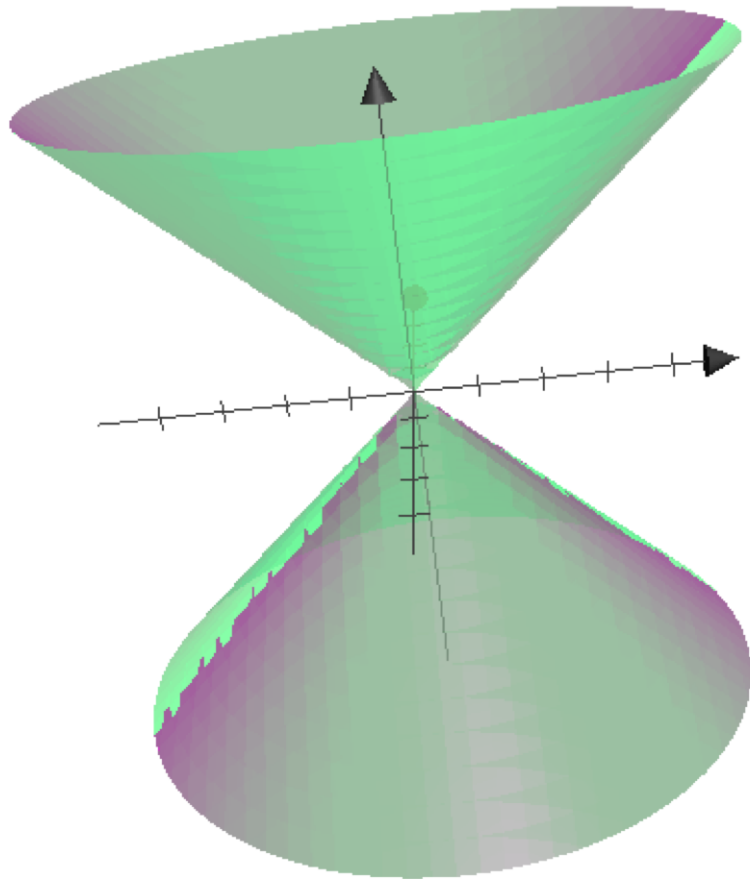
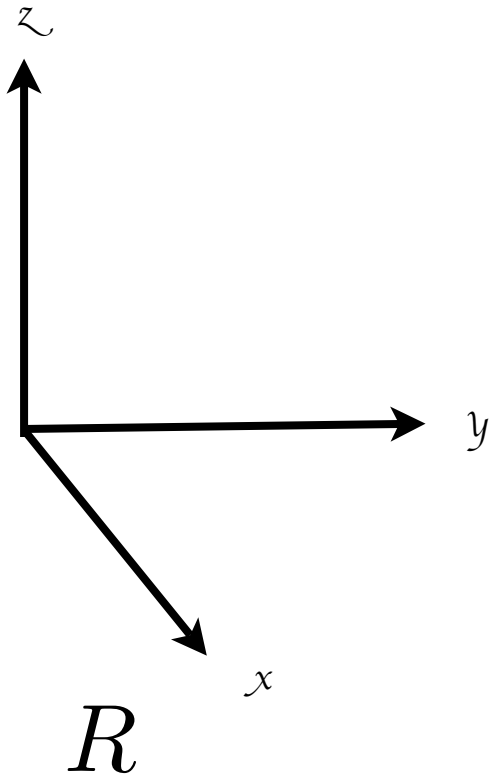


Hyperbolic Geometry and Special Relativity



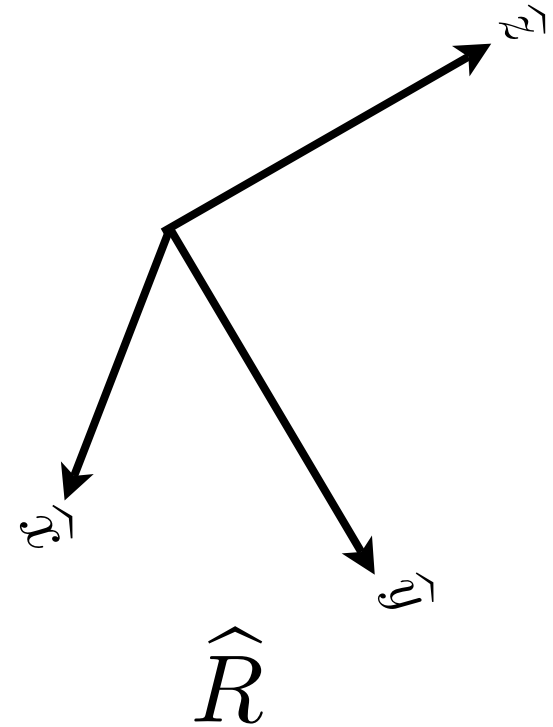
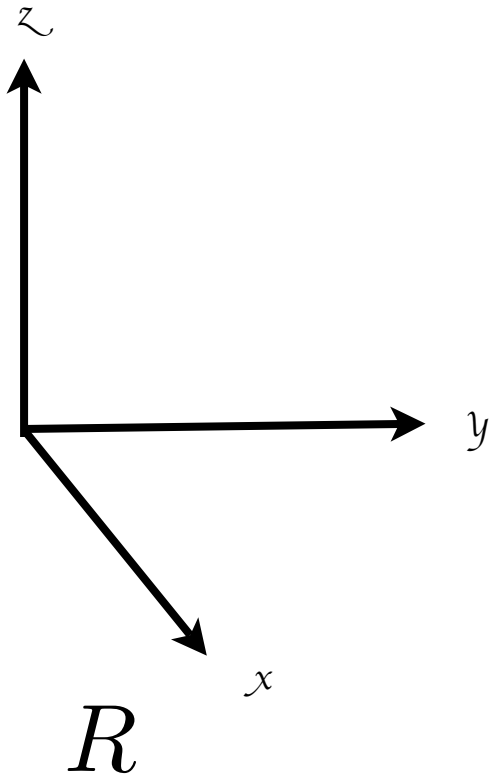
Classical Mechanics

- To solve physical problems we must choose a reference frame



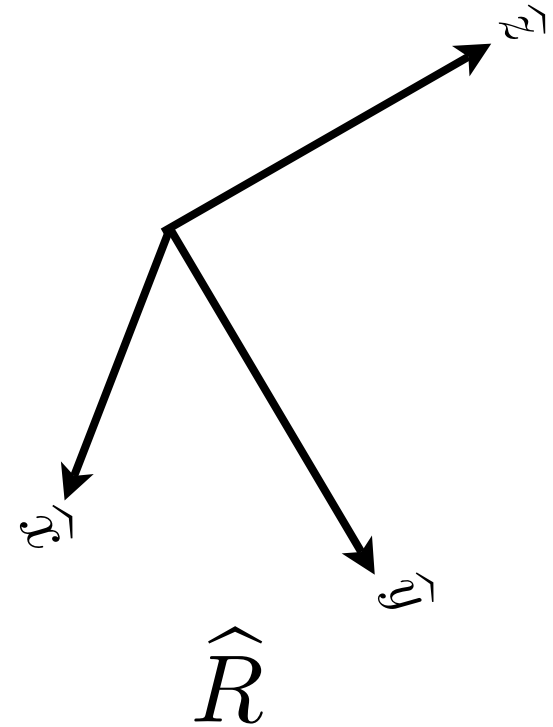
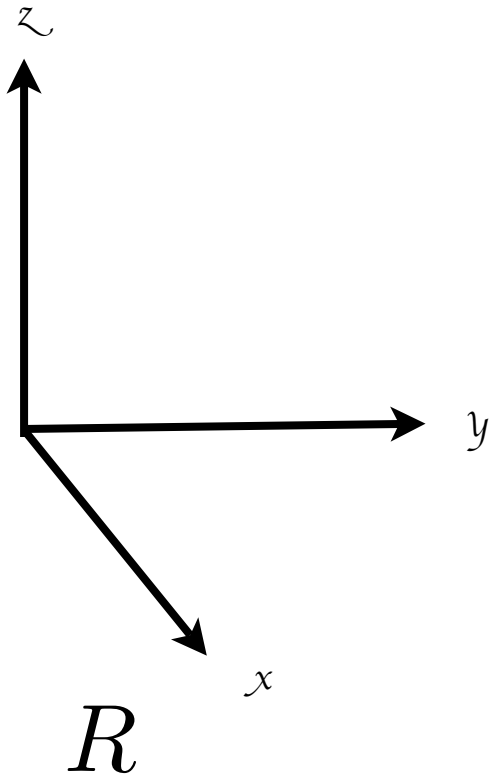
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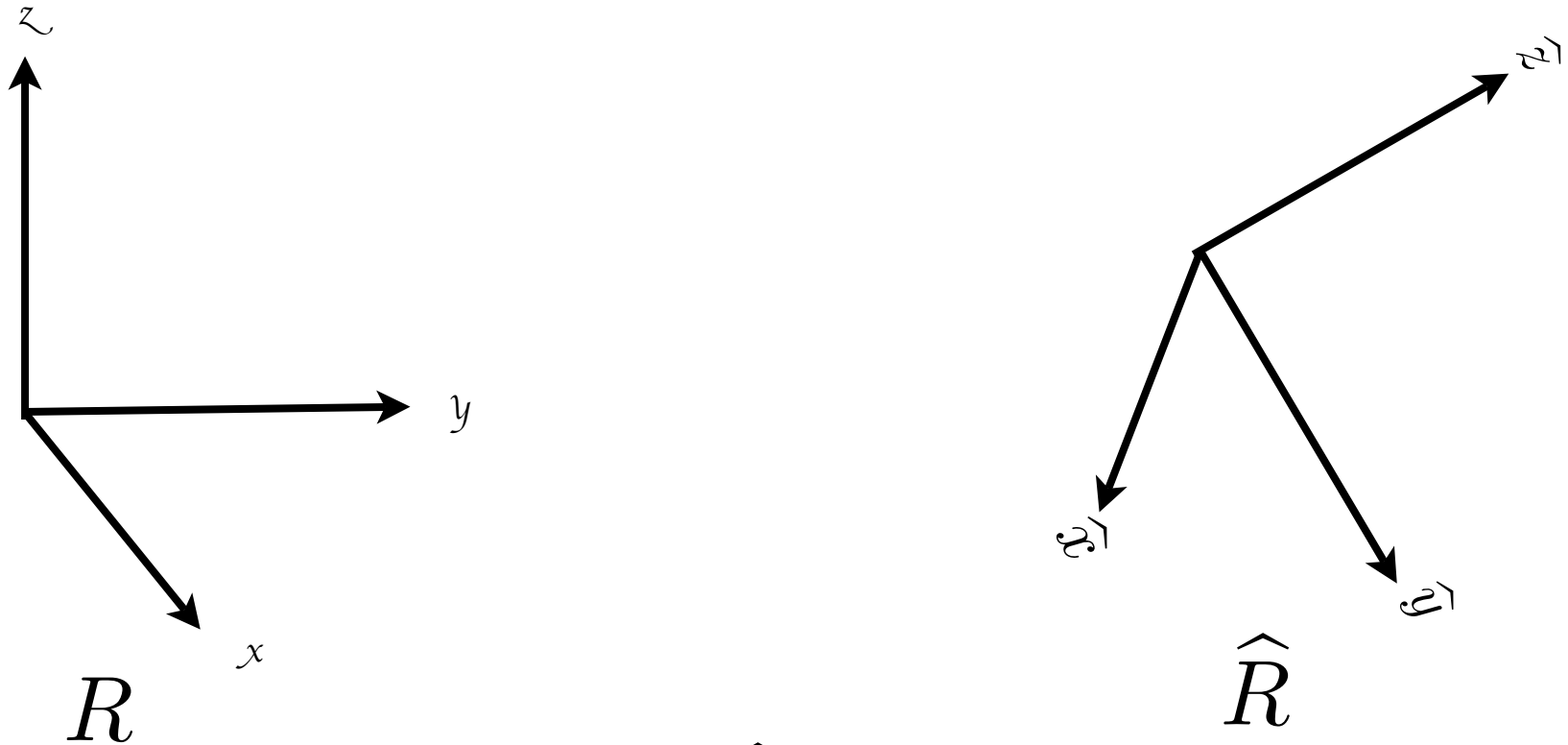
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$$\mathbf{x} = H\hat{\mathbf{x}} + T$$

Classical Mechanics

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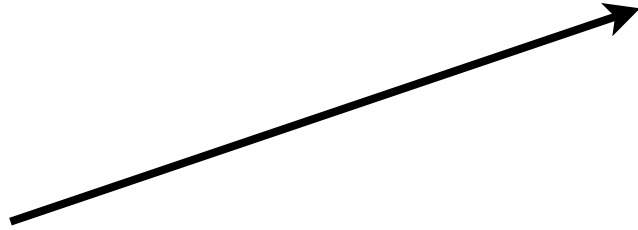


$$\mathbf{x} = H\hat{\mathbf{x}} + T$$

$$H \in SO(n) \quad T \in \mathbb{R}^n$$

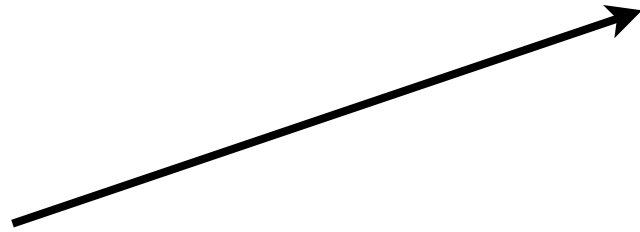
Classical Mechanics

- Newton's 1st Law: w/o forces, bodies move in straight lines w/o accel.



Classical Mechanics

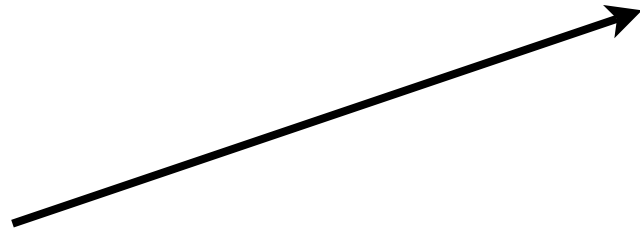
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- Law of Inertia: There exist reference frames s.t. Newton 1 holds.

Classical Mechanics

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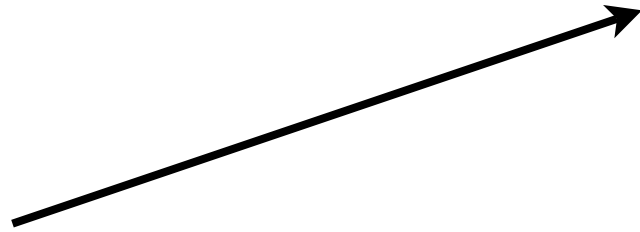
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inertial frames

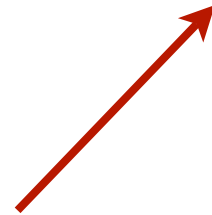
A red arrow pointing upwards and to the right, pointing towards the text "There exist reference frames" in the Law of Inertia bullet point.

Classical Mechanics

- Newton's 1st Law: w/o forces, bodies move in straight lines w/o accel.



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inertial frames

- *Galilean Transformations* are affine change of coords. that preserve Newton's laws.

Classical Mechanics

• *Galilean Transformations* are affine change of coords. that preserve Newton's laws.

$$\begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ v_1 & & & \\ v_2 & \mathbf{H} & & \\ v_3 & & & \end{pmatrix} \begin{pmatrix} \hat{t} \\ \hat{x} \\ \hat{y} \\ \hat{z} \end{pmatrix} + C$$

v H C are constant

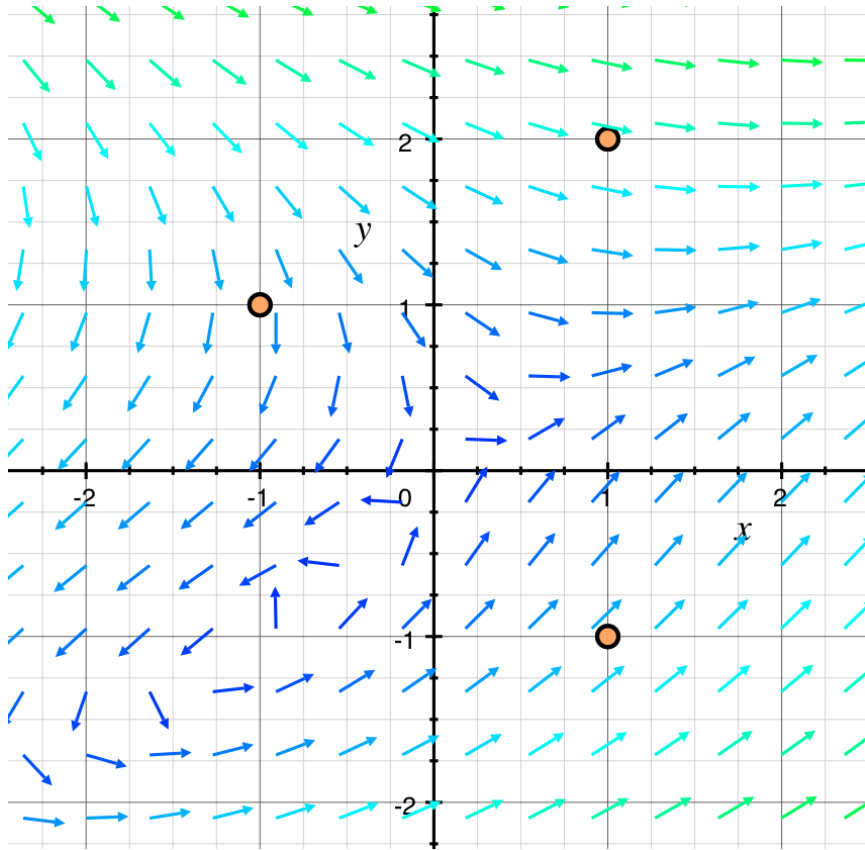
$$H \in SO(n)$$

• *Galilean Transformations* preserve time intervals and (euclidean) distance in space

Maxwell's Equations

E: electric field

B: magnetic field



1. Superposition
2. A stationary point generates no magnetic field and

$$\mathbf{E} = \frac{ke\mathbf{r}}{r^3}$$

3. A point charge with velocity v generates a magnetic field

$$\mathbf{B} = \frac{k'e(\mathbf{v} \times \mathbf{r})}{r^3}$$

Corollary (Lorentz): $\mathbf{F} = e(\mathbf{E} + \mathbf{v} \times \mathbf{B})$

Maxwell's Equations are not invariant

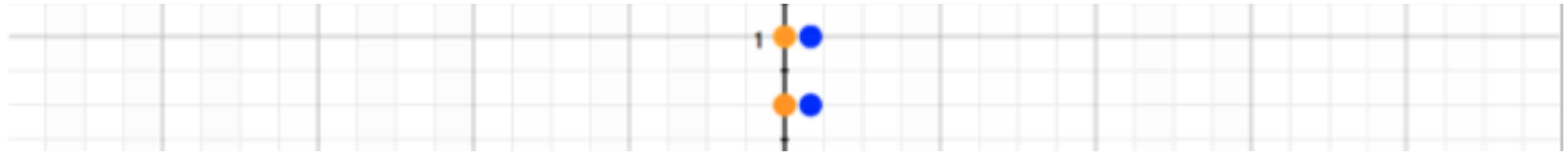


Maxwell's Equations are not invariant



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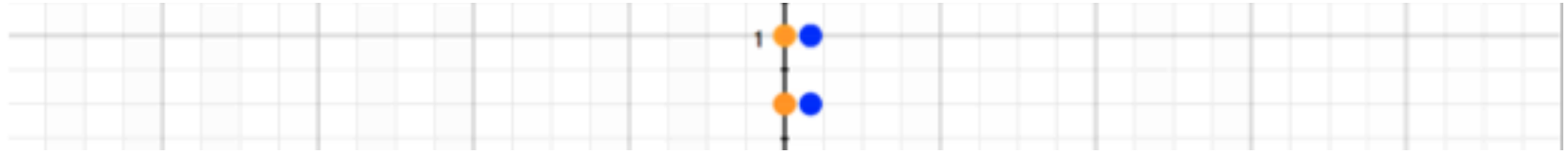
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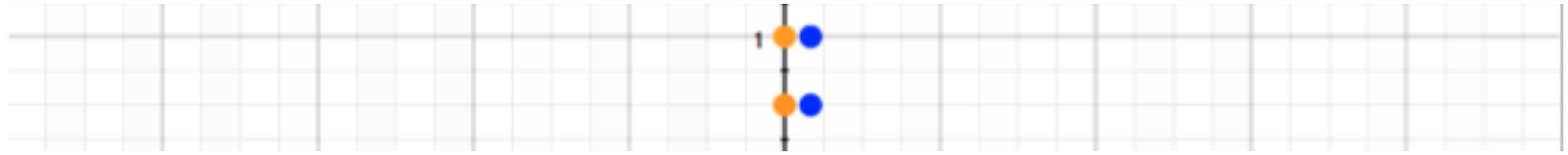
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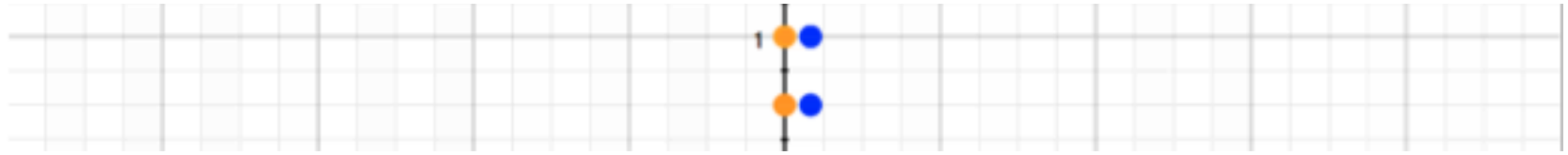
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and by switching the roles:

$$\mathbf{E} = \hat{\mathbf{E}} - \mathbf{v} \times \hat{\mathbf{B}}$$

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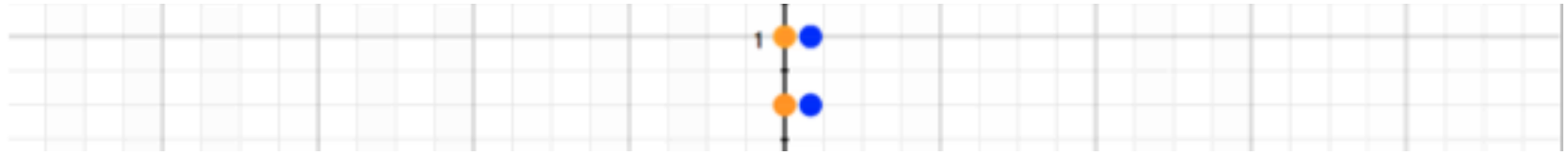
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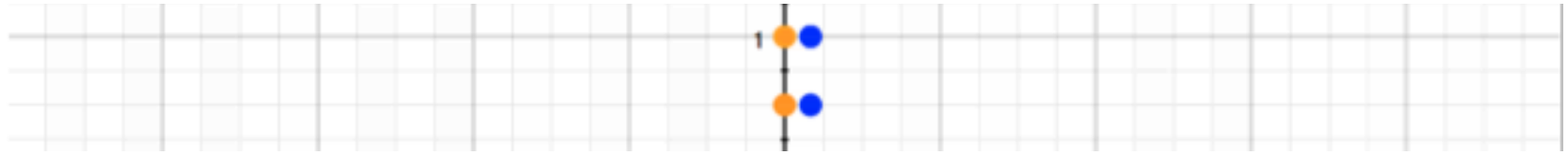
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but: $\mathbf{B} = 0$ and $\hat{\mathbf{B}} = -\frac{\mu_0 e(\mathbf{v} \times \mathbf{r})}{4\pi r^3}$ by (EM 3).

Lorentz Transformations

We assume:

- Transformation is affine (Newton's 1st Law is preserved)
 - Light travels at constant velocity and in straight lines. Hence photon world lines are of the form:
-
- No physical effect is transferred faster than light.
 - Only (not accelerative) relative motion can be detected.

Lorentz Transformations

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- Light travels at constant velocity and in straight lines. Hence photon world lines are of the form:

$$\mathbf{x} = \mathbf{u}t + \mathbf{a}$$

$$||\mathbf{u}||^2 = c^2$$

- No physical effect is transferred faster than light.
- Only (not accelerative) relative motion can be detected.

Lorentz Transformations are affine

$$\mathbf{x} = L\hat{\mathbf{x}} + C$$


$$L = \begin{pmatrix} \gamma & - & - & - \\ - & - & - & - \\ - & - & - & - \\ - & - & - & - \end{pmatrix}$$

$$t = \gamma\hat{t} + \text{constant}$$

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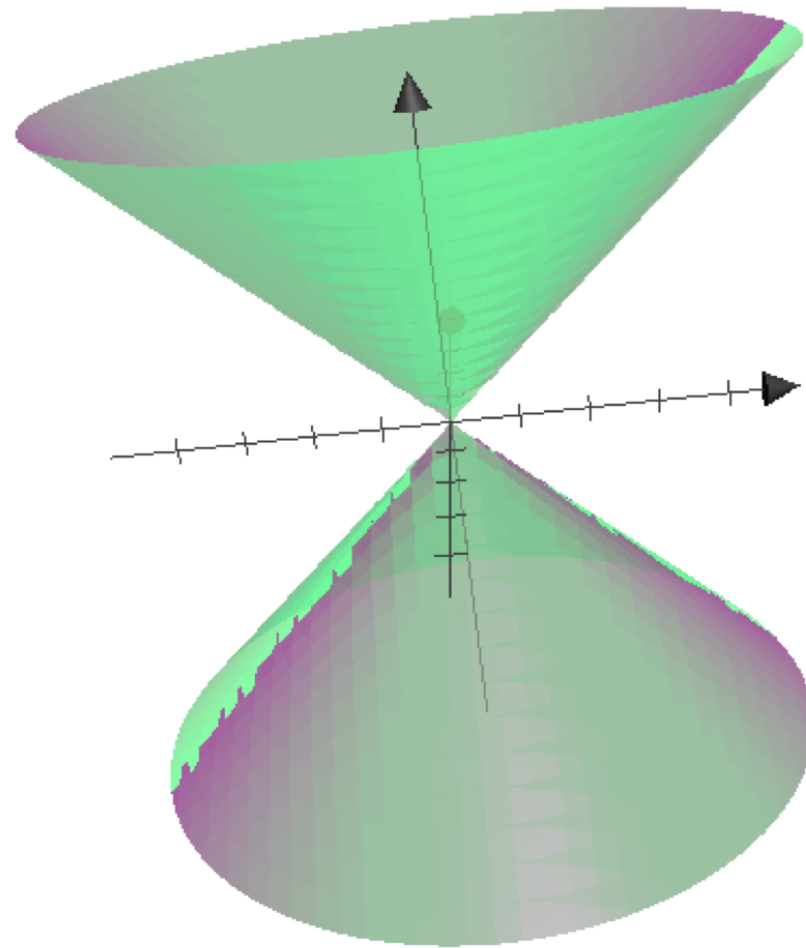
time dilation


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Lorentz Transformations have conical photon world lines

$$ct^2 - x^2 - y^2 - z^2 = 0$$



What's invariant?

The world lines of photons

Event E_i has \mathbf{O} coordinates \mathbf{x}_i .

Event E_i has $\hat{\mathbf{O}}$ coordinates $\hat{\mathbf{x}}_i$.

They are on the world line of a photon iff:

$$\begin{array}{ccc} & D = cT & \\ \text{spatial displacement} \rightarrow & & \leftarrow \text{temporal displacement} \end{array}$$

$$\begin{aligned} c^2(t_2 - t_1)^2 - (x_2 - x_1)^2 - (y_2 - y_1)^2 - (z_2 - z_1)^2 &= 0 \\ c^2(\hat{t}_2 - \hat{t}_1)^2 - (\hat{x}_2 - \hat{x}_1)^2 - \dots &= 0 \end{aligned}$$

World Lines of Photons

$$X = \begin{pmatrix} ct_2 \\ x_2 \\ y_2 \\ z_2 \end{pmatrix} - \begin{pmatrix} ct_1 \\ x_1 \\ y_1 \\ z_1 \end{pmatrix} \quad \hat{X} = \begin{pmatrix} \hat{c}\hat{t}_2 \\ \hat{x}_2 \\ \hat{y}_2 \\ \hat{z}_2 \end{pmatrix} - \begin{pmatrix} \hat{c}\hat{t}_1 \\ \hat{x}_1 \\ \hat{y}_1 \\ \hat{z}_1 \end{pmatrix}$$

$$g = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

Need:

$$X^t g X = 0 \Leftrightarrow \hat{X}^T g \hat{X} = 0$$

If $\hat{X} = LX$ then:

$$X^t g X = 0 \Leftrightarrow X^T L^T g L X = 0$$

Minkowski Space $\mathbb{R}^{1,3}$

$$x \circ y = -x_1 y_1 + x_2 y_2 + x_3 y_3 + x_4 y_4$$

$$||x|| = \sqrt{x \circ x}$$

$$x \circ y = ||x|| ||y|| \cosh \eta$$

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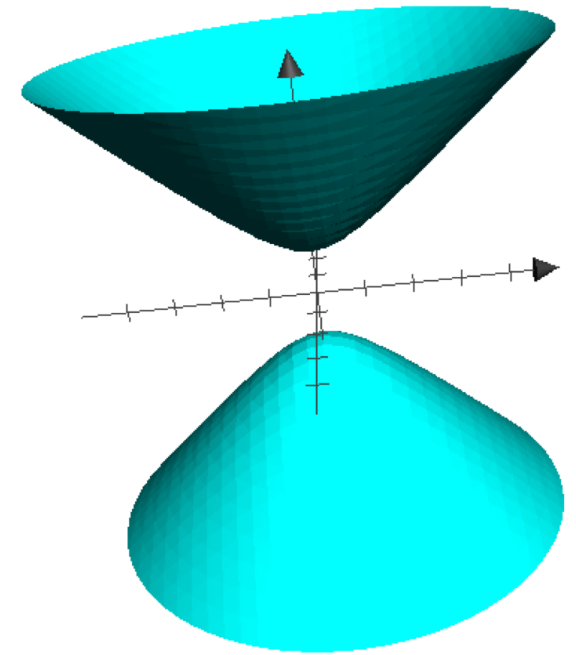
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$$\phi(x) \circ \phi(y) = x \circ y \quad \begin{array}{l} \text{Lorentz} \\ \text{transformation} \end{array}$$

Minkowski Space $\mathbb{R}^{1,3}$

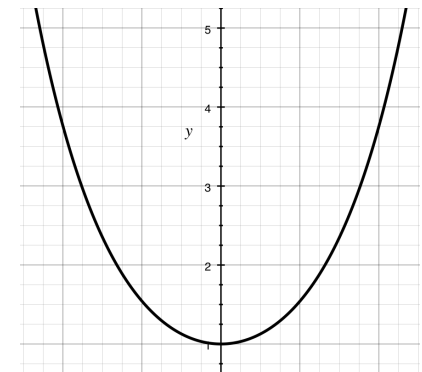
$$F^3 = \{x \in \mathbb{R}^{1,3} : \|x\|^2 = -1\}$$



$$x \circ y = \|x\| \|y\| \cosh \eta$$

$$d_H(x, y) = \eta(x, y)$$

time-like angle



Minkowski Space

Theorem: F^3 with d_H is isometric to \mathbb{H}^3