## Exam # 2, Math 253, Spring 2001

- 1. True or False?
- a. The column vectors of a 4×5 matrix must be linearly dependent.
- b. If a 3×3 matrix A is non-invertible, then the last column of A must be a linear combination of the first two columns of A.
- c. If the rank of a  $9 \times 10$  matrix A is 5, then the kernel of A is 4-dimensional.
- d. If matrix A is similar to B, and A is invertible, then B must be invertible as well.
- e. If A is an invertible  $3\times 3$  matrix and  $\vec{x}$  is a non-zero vector in  $\mathbb{R}^3$ , then the vectors  $\vec{x}$ ,  $A\vec{x}$ , and  $A^2\vec{x}$  must form a basis of  $\mathbb{R}^3$ .
- 2. True or False?
- a. The function  $T(A) = A \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$  is an isomorphism from  $\mathbb{R}^{2\times 2}$  to  $\mathbb{R}^{2\times 2}$ .
- b. The functions f(x) in  $C^{\infty}$  such that  $\int_{-1}^{1} f(x)dx = 0$  form a subspace of  $C^{\infty}$ .
- c. The function T(f) = f + f'' is an isomorphism from  $C^{\infty}$  to  $C^{\infty}$  .
- d. The function  $T(f) = \begin{bmatrix} f(1) & f(-1) \\ f(2) & f(-2) \end{bmatrix}$  is an isomorphism from  $P_4$  to  $\mathbb{R}^{2\times 2}$ .
- e. There exists a two-dimensional subspace V of  $\mathbb{R}^{2\times 2}$  such that all matrices in V are noninvertible.
- 3. Let V be the set of all polynomials f(x) in  $P_3$  such that f'(0) = 0 and f(2) = 0. We are told that V is a subspace of  $P_3$ . Find a basis of V and determine the dimension of V.
- 4. Consider the linear transformation  $T\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_2 \\ x_1 \end{bmatrix}$  from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ . Is there a basis  $\mathfrak{B}$  of  $\mathbb{R}^2$  such that the  $\mathfrak{B}$ -matrix of T is  $\begin{bmatrix} -1 & 2 \\ 0 & 1 \end{bmatrix}$ ? Find such a basis  $\mathfrak{B}$ , or show that none can exist.
- 5. Consider the function  $T(M) = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} M M \begin{bmatrix} 2 & 0 \\ 3 & k \end{bmatrix}$  from  $\mathbb{R}^{2\times 2}$  to  $\mathbb{R}^{2\times 2}$ , where k is an arbitrary constant. We are told that T is a linear transformation.

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- a. For the standard basis  $\mathfrak{B}$  of  $\mathbb{R}^{2\times 2}$ , find the  $\mathfrak{B}$ -matrix B of T. Some of the entries of your matrix B will contain the constant k.
- b. For which values of the constant k is T an isomorphism? Math 253, Spring 2001, Exam # 2, Solutions

# Math 253, Exam # 2, Spring 2001, Solutions

1

- 2. True or False?
- T F The function  $T(A) = A \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$  is an isomorphism from  $\mathbb{R}^{2\times 2}$  to  $\mathbb{R}^{2\times 2}$ .

**True.** Check linearity of T. Since the matrix  $\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$  is invertible, we can write a

formula for the inverse of the transformation  $B = A \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ , namely,  $A = B \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}^{-1}$ .

T F The functions f(x) in  $C^{\infty}$  such that  $\int_{-1}^{1} f(x)dx = 0$  form a subspace of  $C^{\infty}$ .

True. Check the three axioms for a subspace:

- The function f(x) = 0 is the neutral element of  $C^{\infty}$ , and  $\int_{1}^{1} 0 dx = 0$
- It's closed under addition: If  $\int_{-1}^{1} f = 0$  and  $\int_{-1}^{1} g = 0$ , then  $\int_{-1}^{1} (f+g) = \int_{-1}^{1} f + \int_{-1}^{1} g = 0$
- It's closed under scalar multiplication: If  $\int_{-1}^{1} f = 0$ , then  $\int_{-1}^{1} (kf) = k \int_{-1}^{1} f = 0$  for all k.

T F The function T(f) = f + f'' is an isomorphism from  $C^{\infty}$  to  $C^{\infty}$ . False.  $\ker(T) = \{f/f'' + f = 0\} = \{f/f'' = -f\} = \operatorname{span}(\sin x, \cos x) \neq \{0\}$  (see Fact 4.2.3b)

The function T(f) = f(1) is an isomorphism from P to  $\mathbb{R}^{2\times 2}$  file:///Lovejoy%20Lab/Desktop%20Folder/253exam2spring.html (2 of 6) [11/3/2002 1:01:40 AM]

T F The function  $T(f) = \begin{bmatrix} f(1) & f(-1) \\ f(2) & f(-2) \end{bmatrix}$  is an isomorphism from  $P_4$  to  $\mathbb{R}^{2 \times 2}$ .

2

False.  $\dim(P_4) = 5$  but  $\dim(\mathbb{R}^{2\times 2}) = 4$  (see Fact 4.2.3d)

T F There exists a subspace V of  $\mathbb{R}^{2\times 2}$  such that all matrices in V are non-invertible.

**True.** For example,  $V = \begin{bmatrix} a & b \\ 0 & 0 \end{bmatrix}$ : a, b in  $\mathbb{R}$ 

Math 253, Spring 2001, Exam # 2, Solutions

3) Let V be the set of all polynomials f(x) in  $P_3$  such that f'(0) = 0 and f(2) = 0. We are told that V is a subspace of  $P_3$ . Find a basis of V and determine the dimension of V.

Step 1: Write down a general element of the "ambient space",  $P_3$ , involving some arbitrary constants:

$$f(x) = a + bx + cx^2 + dx^3$$

Step 2: Use the conditions that define subspace V to set up a linear system for the arbitrary constants in Step 1.

$$f'(x) = b + 2cx + 3dx^2$$
, so that  $f'(0) = b = 0$   
 $f(2) = a + 2b + 4c + 8d = a + 4c + 8d = 0$ 

Thus the system (in rref) is

$$\begin{array}{cccc}
a & +4c & +8d & =0 \\
b & & =0
\end{array}$$

Step 3: Use Gaussian elimination to solve the system in Step 2 and write down the general element of V:

$$a = -4c - 8d$$
 and  $b = 0$   
general element of  $V$ :  $f(x) = (-4c - 8d) + cx^2 + dx^3$ 

**Step 4:** Write the general element in Step 3 as a linear combination, using the arbitrary constants as the coefficients. Check that the elements of V in this linear combination are linearly independent. Then they will form a basis of V:

$$f(x) = c(x^2 - 4) + d(x^3 - 8)$$
,  
basis of  $V: x^2 - 4, x^3 - 8$ ,  
 $\dim(V) = 2$ 

 $x_1 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ 

4) Consider the linear transformation  $T\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_2 \\ x_1 \end{bmatrix}$  from  $\mathbb{R}^2$  to  $\mathbb{R}^2$ . Is there a basis  $\mathfrak{B}$  of  $\mathbb{R}^2$  such that the  $\mathfrak{B}$ -matrix of T is  $\begin{bmatrix} -1 & 2 \\ 0 & 1 \end{bmatrix}$ ? Find such a basis  $\mathfrak{B}$ , or show that none can exist.

Solution: Refer to the terminology introduced in Section 3.4, involving matrices A, B, and S.

We are told that  $B = \begin{bmatrix} -1 & 2 \\ 0 & 1 \end{bmatrix}$ .

Math 253, Spring 2001, Exam # 2, Solutions

3

Note that 
$$T\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_2 \\ x_1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$
, so that  $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ .

We are looking for an invertible  $S = \begin{bmatrix} x & y \\ z & t \end{bmatrix}$  such that AS = SB; the columns of S will then give us a basis of  $\mathbb{R}^2$  as desired. Now consider the equation

then give us a basis of  $\mathbb{R}^2$  as desired. Now consider the equation

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x & y \\ z & t \end{bmatrix} = \begin{bmatrix} x & y \\ z & t \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 0 & 1 \end{bmatrix} \quad \text{or} \quad \begin{bmatrix} z & t \\ x & y \end{bmatrix} = \begin{bmatrix} -x & 2x + y \\ -z & 2z + t \end{bmatrix}$$

We are left with two equations, z = -x and t = 2x + y (the other two are redundant), so that the general matrix S that solves the equation AS = SB is of the form

$$S = \begin{bmatrix} x & y \\ -x & 2x + y \end{bmatrix}$$

We need to choose values for x and y that make S invertible; one possible choice is x = 1, y = 0. This gives  $S = \begin{bmatrix} 1 & 0 \\ -1 & 2 \end{bmatrix}$  and the basis  $\mathfrak{B}$  consisting of  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$  and  $\begin{bmatrix} 0 \\ 2 \end{bmatrix}$ .

General solution: 
$$\begin{bmatrix} x \\ -x \end{bmatrix}$$
,  $\begin{bmatrix} y \\ 2x+y \end{bmatrix}$ , as long as  $x \neq 0$  and  $y \neq -x$ 

General solution: 
$$\begin{vmatrix} x \\ -x \end{vmatrix}$$
, as long as  $x \neq 0$  and  $y \neq -x$ 

- 5) Consider the function  $T(M) = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} M M \begin{bmatrix} 2 & 0 \\ 3 & k \end{bmatrix}$  from  $\mathbb{R}^{2\times 2}$  to  $\mathbb{R}^{2\times 2}$ , where k is an arbitrary constant. We are told that T is a linear transformation.
- a) For the standard basis B of R<sup>2×2</sup>, find the B-matrix B of T. Some of the entries of your matrix B will contain the constant k.

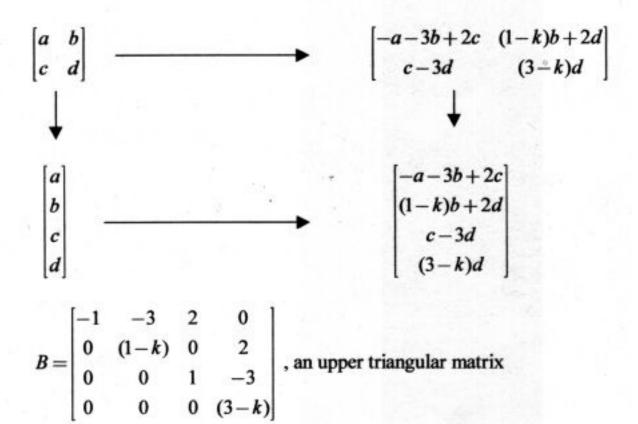
#### Solution:

$$T \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 3 & k \end{bmatrix}$$
$$= \begin{bmatrix} a+2c & b+2d \\ 3c & 3d \end{bmatrix} - \begin{bmatrix} 2a+3b & kb \\ 2c+3d & kd \end{bmatrix} = \begin{bmatrix} -a-3b+2c & (1-k)b+2d \\ c-3d & (3-k)d \end{bmatrix}$$

Now write input and output in coordinates with respect to the standard basis.

#### Math 253, Spring 2001, Exam # 2, Solutions

Thus



### b) For which values of the constant k is T an isomorphism?

Solution: T is an isomorphism iff matrix B is invertible. Use either the determinant or Gaussian elimination to see that a triangular matrix is invertible iff all diagonal entries are nonzero.

Thus T is an isomorphism iff the constant k is neither 1 nor 3.