

Multivariable Calculus Spring 2018

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TEXTBOOK REFERENCE:

- Vector Calculus, Colley, 4th Edition: §4.3, 4.4

LAGRANGE MULTIPLIERS; LINEAR REGRESSION

Keywords: the method of Lagrange multipliers, linear regression, polynomial regression

Let f(x,y), g(x,y) be differentiable functions. We are interested in the **contstrained** optimisation problem

maximise/minimise
$$f(x,y)$$

subject to $g(x,y) = 0$

Remark: An equation h(x,y) = c, c constant, is called a **constraint**. Note that any constraint h(x,y) = c can be rearranged to a constraint of the form g(x,y) = 0 by letting g(x,y) = h(x,y) - c.

In the last lecture we saw that the solutions to this problem - the **constrained extrema** - came in two flavours:

- (I) the points (x, y) satisfying $\nabla f(x, y) = 0$ and g(x, y) = 0;
- (II) the points (x, y) satisfying $\nabla f(x, y) = \lambda \nabla g(x, y)$ and g(x, y) = 0, for some nonzero λ , called a **Lagrange multiplier**.

Note that type (I) points can be considered to be type (II) points for the case $\lambda=0$.

We generalise to the setting of several variables:

Method of Lagrange multipliers: single constraint

Let $f(\underline{x})$, $g(\underline{x})$ be differentiable functions of n variables. If \underline{x} is a solution to the constrained optimisation problem

maximise/minimise
$$f(\underline{x})$$

subject to $g(\underline{x}) = 0$

then there exists some λ such that (x, λ) is a solution to the equation

$$\nabla f(\underline{x}) = \lambda \nabla g(\underline{x})$$

Remark: The method of Lagrange multipliers can be extended to the case of multiple constraints $g_1(\underline{x}) = \ldots = g_k(\underline{x}) = 0$. In this case there are two flavours of constrained extrema:

- (I) the points \underline{x} satisfying $\nabla f(\underline{x}) = 0$ and $g_1(\underline{x}) = \ldots = g_k(\underline{x}) = 0$;
- (II) the points \underline{x} satisfying $\nabla f(\underline{x}) = \sum_{i=1}^k \lambda_i \nabla g_i(\underline{x})$ and $g_1(\underline{x}) = \ldots = g_k(\underline{x}) = 0$, for some $\lambda_1, \ldots, \lambda_k$ (not all equal to zero).

The gradient condition states that $\nabla f(\underline{x})$ is orthogonal to the tangent space of the space defined by $g_1 = \ldots = g_k = 0$. For details see p.284 of the textbook.

Example: Model the surface of the Earth by the unit sphere $x^2 + y^2 + z^2 = 1$. A satellite is orbiting the earth at a fixed height - in our model the satellite's orbit is constrained to lie in the sphere $x^2 + y^2 + z^2 = 9$. Assume we are standing at (1,0,0) on the surface of the Earth. Let's use Lagrange multipliers to confirm the obvious(?) geometric fact: the satellite is closest to our position when the satellite is at (3,0,0).

We model this problem as a constrained optimisation problem:

minimise
$$d(x, y, z) = (x - 1)^2 + y^2 + z^2$$

subject to $g(x, y, z) = x^2 + y^2 + z^2 - 9 = 0$

Solution:

Applications of Extrema

Linear regression A set S of k points in the plane

$$S = \{(x_1, y_1), \dots, (x_k, y_k)\}$$

can be interreted as a data set relating two quantities x and y. For example, x could represent SAT scores and y could represent college grades.

We want to understand what the general linear correlation is between the quantities x and y i.e. we want to find the **line of best fit** y = mx + b. Mathematically, we want to solve the optimisation problem:

minimise
$$D(m,b) = (y_1 - (mx_1 + b))^2 + \ldots + (y_k - (mx_k + b))^2$$

Diagram:

We need to find the extrema of the function D. We compute ∇D :

$$\frac{\partial D}{\partial m} = \underline{\hspace{1cm}}$$

$$\frac{\partial D}{\partial b} = \underline{\hspace{1cm}}$$

Setting both partial derivatives equal to zero gives the equations

$$(\sum x_i^2)m + (\sum x_i)b = \sum x_i y_i$$

$$(\sum x_i)m + nb = \sum y_i$$

This is a system of linear equations in the two variables m and b. We solve to obtain the single solution:

This approach can be used to solve more general **polynomial regression**. For example, we could try to determine a **parabola of best fit** $y = ax^2 + bx + c$. Then, we aim to minimise

$$D(a, b, c) = \underline{\hspace{1cm}}$$