

## PRACTICE EXAMINATION III

## Instructions:

- You *must* attempt Problem 1.
- Please attempt at least five of Problems 2, 3, 4, 5, 6, 7, 8.
- If you attempt all eight problems then your final score will be the sum of your score for Problem 1 and the scores for the five remaining problems receiving the highest number points.
- Calculators are not permitted.
- 1. (20 points) True/False:
  - (a) Let  $\underline{F}(x,y) = \begin{bmatrix} u(x,y) \\ v(x,y) \end{bmatrix}$ . If  $\underline{F}$  is conservative then  $u_y = v_x$ .
  - (b) Every function f(x, y) defined on  $\mathbb{R}^2$  has a local maximum or local minimum.
  - (c) If f(x,y) is a continuous function then  $\int_0^1 \int_x^1 f(x,y) dy dx = \int_0^1 \int_y^1 f(x,y) dx dy$
  - (d) If C is a closed oriented curve and  $\underline{F}$  is a vector field satisfying  $\int_C \underline{F} \cdot d\underline{r} = 0$  then  $\underline{F}$  is conservative.
  - (e) If  $\underline{u}, \underline{v}$  are vectors then  $|\underline{u} \times \underline{v}|$  is the area of the parallelogram spanned by  $\underline{u}, \underline{v}$ .
  - (f)  $3\nabla f = \frac{d}{dt}f(x+t,y+t,z+t)$
  - (g) The vector line integral of  $\underline{F}$  along the ellipse  $x^2 + 5y^2 = 1$  is zero.
  - (h) If  $\underline{u}, \underline{v}, \underline{w} \in \mathbb{R}^3$  lie in a common plane then  $\underline{u} \cdot (\underline{v} + \underline{u}) \times \underline{w} = 0$ .
  - (i) Consider the surface  $S: z^2 = f(x,y)$ . If  $P = (x, y, \sqrt{f(x,y)})$  is a point on S with maximal distance from (0,0,0) then P is a local maximum of  $g(x,y) = x^2 + y^2 + f(x,y)$ .
  - (j) Using linear approximation, the value  $\sqrt{101 \cdot 10002}$  is estimated as  $1000 + 5 + \frac{1}{10}$ .
- 2. Let P = (2, 1, 1), Q = (1, 0, -1), R = (0, -1, 2).
  - (a) Compute  $\overrightarrow{PQ} \times \overrightarrow{PR}$ .
  - (b) Write down the equation of the plane  $\Pi$ : ax + by + cz = d containing the points P, Q, R.
  - (c) Find the distance from the origin to  $\Pi$ .

3. Let 
$$\underline{F}(x,y) = \begin{bmatrix} x^2 - 2xye^{-x^2} + 2y \\ e^{-x^2} + 2x + \cos(y) \end{bmatrix}$$
.

- (a) Show that  $\underline{F}$  is conservative by finding a potential function f(x, y) such that  $\nabla f = \underline{F}$ .
- (b) If C is the oriented curve going from (1,0) to (-1,0) along the semicircle  $x^2 + y^2 = 1$ ,  $y \ge 0$ , evaluate  $\int_C \underline{F} \cdot d\underline{r}$
- 4. Consider the spheres

$$S_1: x^2 + y^2 + z^2 = 6,$$
  $S_2: (x-3)^2 + y^2 + (z+1)^2 = 16.$ 

- (a) Determine the tangent plane to  $S_1$  at the point (1, 1, 2) and the tangent plane to  $S_2$  at the point (-1, 0, -1)
- (b) Find a parameterisation of the line of intersection L of the tangent planes.
- (c) Determine the distance from the centre of  $S_2$  to L.
- 5. (a) Classify the critical points of the function

$$f(x,y) = x^3 - y^2 - xy + 1$$

- (b) Determine the absolute maximum of f(x, y) on the triangle having vertices (0, 0), (-1, 0), (0, 1)Hint: consider the extrema of f(x, y) on the interior of the triangle and on the boundary of the triangle.)
- 6. (a) Let f(x,y) = x + y and D be the region bounded between the x-axis and and the parabola  $y = 1 x^2, 1 \le x \le 5$ . Compute

$$\int \int_D f dA$$

(b) Evaluate the integral by changing the order of integration

$$\int_0^3 \int_{x^2}^9 x e^{-y^2} dy dx$$

7. (a) Given below is the level curve diagram of a function f(x, y). Mark the points on the circle C where the extrema to the constrained optimisation problem

$$\begin{array}{l} \max. \ f(x,y) \\ \text{subject to } C \end{array}$$

can occur.



(b) Let  $\underline{v} = \begin{bmatrix} 1\\1 \end{bmatrix}$ . Find the point  $P = (x_0, y_0)$  on the ellipse  $E : x^2 + 4y^2 = 1$  such that  $\overrightarrow{OP} \cdot \underline{v}$  is maximised.

- 8. (a) Draw the region D', described in polar coordinates by  $\pi/4 \le \theta \le 3\pi/4$ ,  $0 \le r \le 2$ .
  - (b) Let f(x,y) = y x. Using the linear change of coordinate formula, compute

$$\int \int_{D'} f dA$$

(*Hint:* if  $\theta \in [0, 2\pi]$  then  $M_{\theta} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$  is the matrix corresponding to the 'rotate by  $\theta$  counterclockwise' linear transformation.)