## Some thoughts and advice:

- Please submit solutions to the following problems by Wednesday, February 13th, 1.10pm. You can either submit your solution in class or leave it outside my office.
- You should expect to spend several hours on homework sets. A lot of practice problem-solving is essential to understand the material and skills covered in class. Be organised and do not leave problem sets until the last-minute. Instead, get a good start on the problems as soon as possible.
- When approaching a problem think about the following: do you understand the words used to state the problem? what is the problem asking you to do? can you restate the problem in your own words? have you seen a similar problem worked out in class? is there a similar problem worked out in the textbook? what results/skills did you see in class that might be related to the problem?
If you are stuck for inspiration come to office hours, or send me an email. However, don't just ask for the solution - provide your thought process, the difficulties you are having, and ask a coherent question in complete English sentences.
- Form study groups - get together and work through problem sets. This will make your life easier! You must write your solutions on your own and in your own words.
- You are not allowed to use any additional resources (e.g. stackoverflow.com). If you are concerned then please ask.


## Some linear algebra review

Unless otherwise specified, all vector spaces will have scalar field $\mathbb{C}$.

1. (a) Verify that the set

$$
S=\left\{\left[\begin{array}{c}
1 \\
0 \\
-1
\end{array}\right],\left[\begin{array}{c}
-1 \\
1 \\
0
\end{array}\right],\left[\begin{array}{l}
1 \\
0 \\
1
\end{array}\right]\right\} \subseteq \mathbb{C}^{3}
$$

is a basis.
(b) Determine the $S$-coordinates of $v=\left[\begin{array}{l}1 \\ 1 \\ 1\end{array}\right] \in \mathbb{C}^{3}$.
(c) Determine the $S$-coordinates of an arbitrary vector $\left[\begin{array}{l}a_{1} \\ a_{2} \\ a_{3}\end{array}\right] \in \mathbb{C}^{3}$. (Your solution will be in terms of $\left.a_{1}, a_{2}, a_{3}\right)$
(d) Determine an explicit formula for the $S$-coordinate map $[-]_{S}: \mathbb{C}^{3} \rightarrow \mathbb{C}^{3}$.
2. Let $T: V \rightarrow W$ be a linear map.
(a) Define the kernel of $T$ to be the subset

$$
\operatorname{ker} T=\left\{v \in V \mid T(v)=0_{W} \in W\right\} \subseteq V
$$

Prove that ker $T$ is a subspace of $V$.
(b) Define the image of $T$ to be the subset

$$
\operatorname{im} T=\{w \in W \mid w=T(v) \text { for some } v \in V\} \subseteq W
$$

Prove that im $T$ is a subspace of $W$.
The following result is one of the most important theorems of linear algebra (it can be considered the Fundamental Theorem of Linear Maps).
Rank Theorem: Let $T: V \rightarrow W$ be a linear map, $V$ finite dimensional. Then,

$$
\operatorname{dim} \operatorname{ker} T+\operatorname{dim} \operatorname{im} T=\operatorname{dim} V
$$

3. Consider the subset

$$
U=\left\{\left.\left[\begin{array}{l}
a_{1} \\
a_{2} \\
a_{3} \\
a_{4}
\end{array}\right] \right\rvert\, a_{1}+a_{2}+a_{3}+a_{4}=0\right\} \subseteq \mathbb{C}^{4}
$$

(a) Determine a linear map $T: \mathbb{C}^{4} \rightarrow \mathbb{C}$ so that $U=\operatorname{ker} T$. Conclude that $U \subseteq \mathbb{C}^{4}$ is a subspace.
(b) Show that $\operatorname{im} T=\mathbb{C}$. Deduce that $\operatorname{dim} U=3$.
(c) Find a basis $\mathcal{B}$ of $U$. Make sure you verify that the set you give is, in fact, a basis. (There are an infinite number of possibilities here!)
4. Consider the linear map

$$
L: \mathbb{C}^{4} \rightarrow \mathbb{C}^{4},\left[\begin{array}{l}
a_{1} \\
a_{2} \\
a_{3} \\
a_{4}
\end{array}\right] \mapsto\left[\begin{array}{l}
a_{2} \\
a_{3} \\
a_{4} \\
a_{1}
\end{array}\right]
$$

Recall the subspace $U \subseteq \mathbb{C}^{4}$ and your basis $\mathcal{B}$ from the previous problem.
(a) Show that $L(u) \in U$, for any $u \in U$. Deduce that $L$ restricts to a linear map

$$
L_{\mid U}: U \rightarrow U, u \mapsto L(u)
$$

(The last part is quite straightforward (i.e. one or two sentences of explanation) as there's only two things to consider: (1) $L_{\mid U}$ is well-defined, (2) $L_{\mid U}$ is linear)
(b) Determine the matrix of $L_{\mid U}$ with respect to $\mathcal{B}$; your resulting matrix will be $3 \times 3$.

