The final exam is cumulative. The following problems concern only material since Exam 2. You should also use previous exams, practice exams, quizzes, and homework to study.

- (1) Find a parameterization of the surface formed by the graph of $z = x^2 y^2$ with (x, y) in the triangle in the *xy*-plane formed by the *x*-axis, the *y*-axis, and the line y = -x + 1.
- (2) Is the surface in the previous problem a smooth surface? If no, at what points is it not smooth?
- (3) Find a parameterization of the surface formed by rotating the curve $\binom{\cos t + 5}{2 \sin t}$ with $0 \le t \le 2\pi$ around the *y*-axis.
- (4) Consider the surface

$$\mathbf{X}(s,t) = \begin{pmatrix} 2\sin 3t + t\\ \cos 2s\\ t^2 + s^2 \end{pmatrix}, \quad 0 \le t \le \pi/4, \quad 0 \le s \le \pi$$

Find the tangent and normal vectors to **X** at the point $(\pi/6, \pi/6)$. Is the surface smooth?

(5) Suppose that $\mathbf{F}: \mathbb{R}^3 \to \mathbb{R}^3$ is a C¹ vector field, and that $\mathbf{X}: D \to \mathbb{R}^3$ is a smooth, oriented surface. Let $h: E \to D$ be a smooth, orientation reversing change-of coordinate function. Prove that

$$\iint_{\mathbf{X}} \mathbf{F} \cdot d\mathbf{S} = -\iint_{\mathbf{X} \circ h} \mathbf{F} \cdot d\mathbf{S}.$$

(6) Suppose that $f: \mathbb{R}^3 \to \mathbb{R}$ is a C¹ vector field, and that $\mathbf{X}: D \to \mathbb{R}^3$ is a smooth, oriented surface. Let $h: E \to D$ be a smooth change-of coordinate function. Prove that

$$\iint_{\mathbf{X}} f \, dS = \iint_{\mathbf{X} \circ h} f \, dS.$$

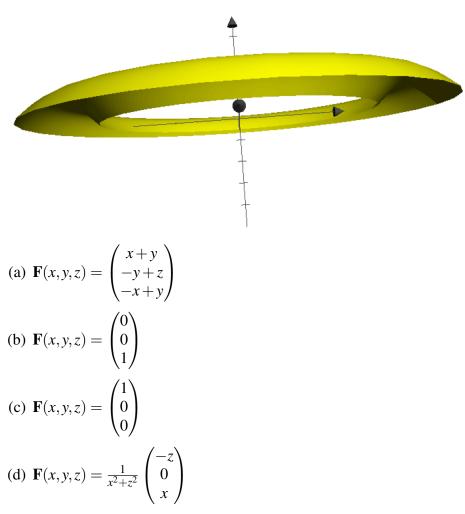
(7) Suppose that $\mathbf{X}: D \to \mathbb{R}^3$ is a smooth, oriented surface with unit normal **n**. Suppose that $\mathbf{F}: \mathbb{R}^3 \to \mathbb{R}^3$ is a C¹ vector field. Prove that

$$\iint_{\mathbf{X}} \mathbf{F} \cdot d\mathbf{S} = \iint_{\mathbf{X}} \mathbf{F} \cdot \mathbf{n} \, dS.$$

- (8) Use the previous result to integrate the vector field $\mathbf{F}(x, y, z) = (x, y, z)$ over the unit sphere (with outward normal) in \mathbb{R}^3 .
- (9) Let *S* be the disc of radius 1 centered at (1,0,0) in \mathbb{R}^3 which is parallel to the *yz*-plane. Orient *S* with normal vector pointing in the direction of the postive *x*-axis. Use the definition of surface integral to calculate the flux of $\mathbf{F}(x, y, z) = (-xy, yz, xz)$ through *S*.
- (10) Use the same surface S and \mathbf{F} as in the previous problem, but now use Stoke's theorem to calculate the flux of the curl of the previous problem.
- (11) Let S ⊂ ℝ³ be an ellipsoid enclosing the origin, oriented outward. Let P ⊂ ℝ³ be a cube enclosing the origin and enclosed by S. Orient P outward. Let F be an incompressible vector field defined on ℝ³ {0}. Prove that the flux of F through P is the same as the flux of F through S.
- (12) Let $\mathbf{F}: \mathbb{R}^3 \to \mathbb{R}^3$. Let **a** be a point in \mathbb{R}^3 . For each $n \in \mathbb{N}$, let V_n be a compact 3-dimensional region containing **a**, such that the regions V_n limit to **a**. Oriente the boundary of V_n outwards. Use the divergence theorem to prove that

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$$\mathbf{F}(\mathbf{a}) = \lim_{n \to \infty} \frac{1}{\operatorname{vol} V_n} \iint_{\partial V_n} \mathbf{F} \cdot d\mathbf{S}$$

- (13) Let *S* be the box with corners $(\pm 1, \pm 1, \pm 1)$, oriented outward. Let $\mathbf{F}(x, y, z) = \begin{pmatrix} xyz \\ xy \\ z \end{pmatrix}$. Find the flux of **F** through *S*. (14) Let *S* be a surface formed by rotating the image of $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} t \\ \sin t \end{pmatrix}$,
 - 14) Let *S* be a surface formed by rotating the image of $\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} t \\ \sin t \end{pmatrix}$, $2\pi \le t \le 3\pi$ around the *y*-axis. Orient *S* so that at the point $(2\pi + \pi/2, 1, 0)$ there is an upward pointing normal vector. For the following vector fields, find the flux of the vector field through *S*. (Hint: there are easy ways and there are hard ways...)



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- (15) Prove that inside a hollow planet there is no gravity. (You may use Gauss' Law of Gravitation.)
- (16) Give a complete, precise statement of both Stokes' theorem and the divergence theorem.