Final Exam

- This exam is due in Professor Taylor's office on Saturday.
- You may not discuss this exam with anybody other than the professor.
- You may use your textbook, the point-set topology notes, your own course notes, and any other handouts distributed in class or placed on the course webpage.
- Other than those resources listed above, you may not use any other resources in completing this exam. This includes other topology texts and online sources.

1. POINT-SET TOPOLOGY

(1) Before beginning this problem, you may wish to read about the one-point compactification of a space on page 90 of your text. Let (X, d) be a connected non-compact metric space. Let x₀ ∈ X and suppose that X has the property that B_r = {y ∈ X : d(x₀, y) ≤ r} is compact for every r > 0. Let W_r = {y ∈ X : d(x, y) ≥ r}. Notice that W_r is closed. Let {r_n} be an sequence of real numbers so that lim_{n→∞} r_n = ∞. For each r_n let U(r_n) be a non-compact connected component of W_{rn}. The sequence {U(r_n)} is called a **pre-end** of X if

$$U(r_1) \supset U(r_2) \supset U(r_3) \dots$$

Suppose that $\{r_n\}$ and $\{s_n\}$ are sequences so that $\{U(r_n)\}$ and $\{U(s_n)\}$ are pre-ends of X. Define $\{U(r_n)\} \sim \{U(s_n)\}$ iff for every m there exists n with $U(s_m) \supset U(r_n)$.

We will also need the following definition. Define

$$U(r_n) = U(r_n) \cap \{ y \in X : d(x_0, y) > r_n \}.$$

Notice that although $U(r_n)$ may not be open, $U(r_n)$ is open.

- (a) Give an example of a pre-end of the metric space $\mathbb R$ with the usual metric.
- (b) Prove that \sim is an equivalence relation on the set of pre-ends. Define an **end** of X to be an equivalence class of pre-ends.
- (c) Explain why \mathbb{R}^n for $n \ge 2$ has exactly one end and why \mathbb{R} has two ends.

Let J be the collection of ends of X. We will now think of J as a collection of points which are not in X and we will topologize $\widehat{X} = X \cup J$ by defining a generating set for the topology. Let \mathcal{B} consist of sets V such that either $V \subset X$ and V is open or $V = \mathring{U}(r_n) \cup \{u\}$ for some $u \in J$ and some $U(r_n)$ in a preend representing the equivalence class u. Give \widehat{X} the topology generated by \mathcal{B} .

- (d) Assume that for all $x \in X$, there exists $\epsilon > 0$ so that $\{y \in X : d(x, y) \le \epsilon\}$ is compact. Prove that \widehat{X} is Hausdorff.
- (e) Suppose that X has finitely many ends. Let V be an open cover of X by sets in B. Prove that V has a finite subcover of X. (In fact, X is compact, but answering this problem is easier than proving that fact.)
- (f) Bonus: Give X/J the quotient topology. Prove that this is homeomorphic to the one-point compactification of X.

2. PROBLEMS CONCERNING MAJOR THEOREMS PROVED IN CLASS

Do three of the following 5 problems.

(1) Let p = (1,0) ∈ S¹ ⊂ ℝ². In a homework exercise, you proved that given a loop f: I → S¹, based at p, f can be homotoped (without moving the basepoint) to either a constant map or to a map which is monotonic on S¹. In order to show that π(S¹, p) is isomorphic to Z it remains to show that no monotonic based loop is homotopic to a constant map. In this problem you will use Sperner's lemma to partially achieve that goal.

Prove the following:

Let $f: I \to S^1$ be the based loop which travels monotonically around S^1 exactly once in a counterclockwise direction. (That is, $f(s) = (\cos(2\pi s), \sin(2\pi s))$). Let f^k denote $f \cdot f \cdot \ldots f$ (k times). Prove that if k is odd, then f^k is not homotopic to a constant map by a basepoint preserving homotopy.

Hint: Suppose that such a homotopy $F: I \times I \to S^1$ exists. Give S^1 the triangulation with 3 vertices. Think of $I \times I$ as a square. Triangulate $I \times I$ so that there are no vertices on the interiors of the side or top edges and so that there are 3k vertices on the bottom edge. Use the strong version of the simplicial approximation theorem (Theorem 3.18 in the text) make F "nice" with respect to the triangulations. Call the vertices of S^1 , w_0 , w_1 , and w_2 . Let $v \in I \times I$ be a vertex. Give v the label i if $F(v) = w_i$. Then use Theorem 2.25.

- (2) In class we proved the Polygonal Jordan Curve Theorem. Recall the proof. Let $R \subset \mathbb{R}^2$ be the square $[0,1] \times [0,1]$. Let $T^2 = R/\sim$ be the torus resulting from gluing opposite sides of R. Let $q: R \to T^2$ be the quotient map.
 - (a) Find a non-intersecting polygonal curve $P \subset R$ so that $q(P) \subset T^2$ is a closed curve which doesn't intersect itself and is such that $T^2 q(P)$ has exactly one connected component.
 - (b) Give a careful explanation of why the proof of the Polygonal Jordan Curve Theorem does **not** also show: for every polygonal curve P ⊂ R with q(P) a non-self-intersecting closed curve, T² - q(P) has exactly two connected components. (In other words, where does the proof of the polygonal Jordan Curve Theorem fail if we try to use it to study curves on a torus?)
 - (c) Outline a proof of the following theorem: Let \mathcal{T} be a triangulation of \mathbb{R}^3 with each simplex of \mathcal{T} a geometric simplex (i.e. the convex hull of affinely independent points). Suppose that

 $S \subset \mathbb{R}^3$ is the union of 2-simplices from \mathcal{T} and suppose that S is homeomorphic to a connected orientable surface. (In fact, it is impossible for S to be homeomorphic to a non-orientable surface.) Then $\mathbb{R}^3 - S$ has exactly two connected components.

- (3) Use the Invariance of Dimension Theorem (Theorem 2.8) to prove that if M is an m-manifold without boundary and if N is an nmanifold without boundary and if M is homeomorphic to N then m = n. (Recall that by the definition of manifold, if $x \in M$ then there is an open set containing x which is homeomorphic to an open set in \mathbb{R}^m .)
- (4) In class we proved the Brouwer Fixed Point Theorem. In this problem you will explore what happens when the hypotheses are relaxed.
 - (a) Let A^2 denote the annulus. Find a continuous function $f: A^2 \rightarrow A^2$ which has no fixed points.
 - (b) Find a continuous function $f: S^2 \to S^2$ which has no fixed points.
 - (c) Find a non-continuous function $f: D^2 \to D^2$ which has no fixed points. (D^2 denotes the closed unit disc.)
 - (d) Let D denote the open unit disc in \mathbb{R}^2 . Find a continuous function $f: D \to D$ without fixed points. (Hint: Recall that D is homeomorphic to \mathbb{R}^2 .)
- (5) Consider the surface S pictured below. Let S_1 be obtained by gluing a disc to the boundary of S. Let S_2 be obtained by gluing a Möbius band to the boundary of S. Use the classification of surfaces theorem to identify S_1 and S_2 as S^2 , nT^2 , or $m\mathbb{P}^2$ for some n or m.

3. Algebraic Topology

Do **three** of the following three problems. If you elect not to do a certain problem you may still use it in the other problems, if you wish.

- (1) Let X and Y be path connected topological spaces and let $p \in X$ and $q \in Y$. Let $r = (p,q) \in X \times Y$. Prove that $\pi_1(X \times Y, r)$ is isomorphic to $\pi_1(X, p) \times \pi_1(Y, q)$.
- (2) Let S be a connected closed orientable surface. Prove that if χ(S) < 0 then π₁(S, p) is not abelian. That is, there exists a, b ∈ π₁(S, p) such that ab ≠ ba. You may use the fact that a simple closed curve in a surface is homotopic to a constant loop if and only if it is the boundary of a disc in the surface.
- (3) Let S and T each be a connected closed surface and suppose that f: S → T is a continuus map. We say that f is **incompressible** if f_{*}: π₁(S, p) → π₁(T, f(p)) is injective.
 - (a) Suppose that S is a 2-sphere. Prove that f is incompressible.
 - (b) Suppose that S is the projective plane and that f is incompressible. Prove that T is non-orientable. You may use the fact that if T is an orientable surface, then no non-trivial element has finite order. That is, if T is orientable and if g is a based loop in T which is not homotopic (by a basepoint preserving homotopy) to a constant map then $g^n = g \cdot g \cdot g \dots \cdot g$ is not homotopic (by a basepoint preserving homotopy) to a constant map.
 - (c) Suppose that T is the torus, that S is orientable, and that f is incompressible. Prove that S is either the torus or the 2-sphere
- (4) Let S be a surface and recall that a continuous function f: S → S induces a homomorphism f_{*}: π₁(S, x₀) → π₁(S, x₀). It is a fact that if two orientation preserving maps induce the same homomorphisms on π₁(S, x₀) then the maps are homotopic. (This is not necessarily true if we work with topological spaces other than surfaces.)
 - (a) Prove that if $f: S \to S$ is a homeomorphism then f_* is an isomorphism. (Hint: Consider the map induced by the homeomorphism $f \circ f^{-1}$.)
 - (b) Using the fact mentioned above, prove that a 2–sphere has exactly one orientation-preserving homeomorphism, up to homotopy.
 - (c) Using the fact mentioned above, explain why orientation preserving homeomorphisms of the torus T^2 to itself can be classified (up to homotopy) by 2×2 matrices with integer entries whose inverse matrices also have integer entries.

(5) Let X be a topological space and suppose that A ⊂ X. A retraction r: X → A is a continuous map such that r(a) = a for all a ∈ A. A deformation retraction of X onto A is a retraction r: X → A such that there exists a homotopy R: X × I → X such that for all x ∈ X, a ∈ A, and t ∈ I, R(x,0) = x, R(x,1) = r(x) and R(a,t) = a. Suppose that there exists a deformation retraction of X onto A. Let i: A → X be the inclusion map. (I.e. i(a) = a.). Prove that

$$i_*: \pi_1(A, a_0) \to \pi_1(X, x_0)$$

is an isomorphism. Use this to prove that if S is a surface then S and $S \times I$ have the same fundamental group.